Anand Balakrishnan

➡ anandbal [at] usc [dot] edu S anandb.dev S github.com/anand-bala
✓ Los Angeles, CA, USA

Education	Skills
 Ph.D. Computer Science Ongoing University of Southern California Advisor: Jyotirmoy Deshmukh B.S. Computer Engineering May 2018 University at Buffalo Distinction: Magna Cum Laude 	 Expert (5+ years): C++ (11, 14, 17), Python, ROS (1, 2), PyTorch, Numpy, Scipy Intermediate (2+ years): C (99, 11, 17), Rust Familiar (1-2 years): Jax, Lua Hobby: Zig, OCaml PROJECTS
 <u>RELEVANT EXPERIENCE</u> <u>Research Assistant</u> <i>CPS-VIDA Group, University of Southern California</i> Developed and published several algorithms for designing, verifying, and monitoring autonomous systems for end-to-end safety. <i>Since August 2018.</i> <u>Technical Intern</u> <i>Siemens Corporation</i> 	ed several algorithms for designing, semantics.
 Developed framework to monitor for reliability and consistency of multi-modal sensor data for safety certification of learning-enabled systems. June 2023 - August 2023 ADAS Software Engineering Intern INDI EV, Inc. Assisted in building the initial prototype for Level 2 autonomy 	 Automatix [github:anand-bala/automatix] A library to define and deploy symbolic (weighted) automata on GPUs using matrix operators with the ability to differentiate through them. <i>Python, Jax</i> SELECT PUBLICATIONS
 Assisted in building the initial prototype for Level 2 autonomy from the ground up on a test vehicle as part of a small team. June 2021 – August 2021 Research Intern Toyota Research Institute, North America Developed open-source tool that uses a logical monitoring specification languages for monitoring the output of perception systems (object detectors and trackers). May 2020 – August 2020	 A. Balakrishnan <i>et al.</i>, "Motion Planning for Automata-based Objectives using Efficient Gradient-based Methods," in 2024 <i>IEEE/RSJ International Conference on Intelligent Robots and</i> <i>Systems (IROS)</i>, Accepted, Oct. 2024. A. Balakrishnan <i>et al.</i>, "Model-Free Reinforcement Learning for Spatiotemporal Tasks Using Symbolic Automata," in 202. <i>62nd IEEE Conference on Decision and Control (CDC)</i>, Dec. 2023. DOI: 10.1109/CDC49753.2023.10383559.
 Undergraduate Researcher Distributed Robotics and Networked Embedded Systems Lab, University at Buffalo Deployed a ROS-based system to collect data to assist in testing the performance of Wi-Fi augmented SLAM algorithms in indoor environments. <i>February 2016 – May 2018</i> For more information regarding my research, please refer to my website or my DBPL page (dblp.org/pid/132/8908) 	 A. Balakrishnan <i>et al.</i>, "PerceMon: Online Monitoring for Perception Systems," in <i>Runtime Verification</i>, Oct. 2021. DOI: 10.1007/978-3-030-88494-9_18. A. Balakrishnan and J. V. Deshmukh, "Structured Reward Shaping Using Signal Temporal Logic Specifications," in 2019. <i>IEEE/RSJ International Conference on Intelligent Robots and</i> <i>Systems (IROS)</i>, Nov. 2019, pp. 3481-3486. DOI: 10.1109/IROS40897.2019.8968254.